Constraint Satisfaction Problems (CSPs)

A binary constraint satisfaction problem consists of

- A set of *n* variables $\{x_1, x_2, ..., x_n\}$ with respective *finite* domains $D_1, D_2, ..., D_n$
 - $\text{ let } D = D_1 \cup D_2 \cup \dots \cup D_n$
 - let d be the size of the largest domain
- A set of e binary constraints $\{C_{ij}\}$
 - C_{ij} represents a constraint between variables x_i and x_j specifying the set of legal pairs of values
 - assume that $C_{ij}(u, v) = C_{ji}(v, u)$

Constraint graph

A constraint graph is a directed graph with *n* nodes and *e* edges

- Each variable is a node
- Each constraint C_{ij} is an edge from node x_i to node x_j

Variables $\{x_1, x_2, x_3, x_4, x_5\}$

Constraints

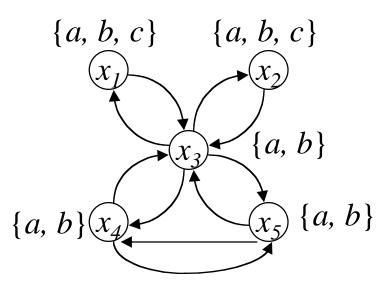
$$-C_{31} = \{(a,b), (a,c), (b,c)\}$$

$$-C_{32} = \{(a,b), (a,c), (b,c)\}$$

$$-C_{34} = \{(a,b), (a,c), (b,c)\}$$

$$-C_{35} = \{(a,b), (a,c), (b,c)\}$$

$$-C_{54} = \{(a,b), (a,c), (b,c)\}$$



Backtrack search

```
procedure bcssp(n)
  consistent = true
  i = initialize()
  loop
     if consistent then (i, consistent) = label(i)
     else(i, consistent) = unlabel(i)
     if i > n then return "solution found"
     else if i = 0 then return "no solution"
  endloop
end bcssp
```

Chronological backtracking: initialize

```
function initialize()

for i = 1 to n

CD_i = D_i /* initialize current domains */

endfor

return 1 /* return the first variable */

end initialize
```

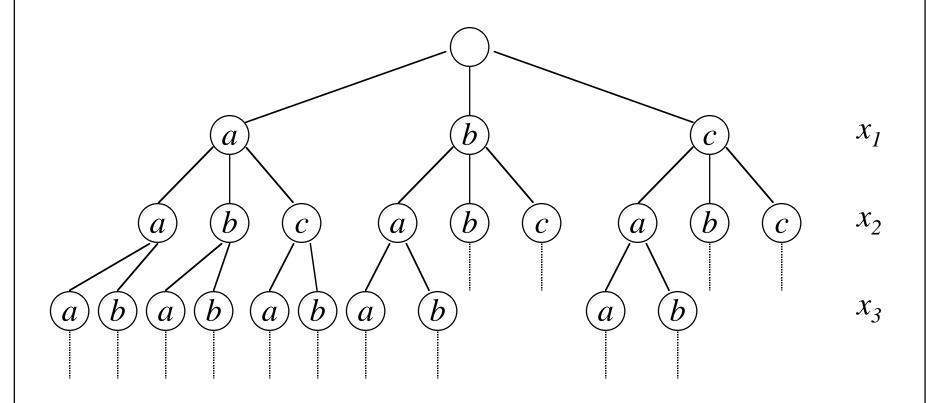
Chronological backtracking: label

```
function bt-label(i)
  for each v_k \in CD_i do
     Set x_i = v_k and consistent = true
     for j from 1 to i-1 do /* Previously assigned variables*/
        if \neg C_{ii}(x_i, x_i) then
           Remove v_k from CD_i and set consistent = false
           Unassign x_i and break inner loop
        endif
     if consistent then return (i+1, true)
   endfor
  return (i, false)
```

Chronological backtracking: unlabel

```
function bt-unlabel(i)
  h = i - 1 /* Backtrack to previous variable */
  CD_i = D_i
  Remove current value assigned to x_h from CD_h
  Unassign x_h
  if CD_h is empty then
     return (h, false)
  else
     return (h, true)
end bt-unlabel
```

Example



Arc consistency

• An arc (i, j) in a constraint graph G is arc consistent with respect to domains D_i and D_j iff

$$\forall v \in D_i, \exists w \in D_j : C_{ij}(v, w)$$

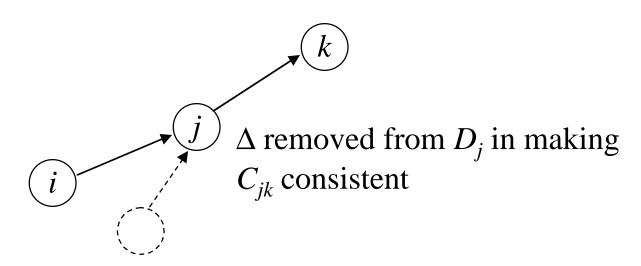
- A graph G is arc consistent iff all its arcs are arc consistent
- Let $P = D_1 \times D_2 \times ... \times D_n$ and $P' = D'_1 \times D'_2 \times ... \times D'_n$ s.t. $P \supseteq P'$. P' is the largest arc consistent domain for G in P iff
 - G is arc consistent wrt P'
 - there is no P'' such that $P \supseteq P'' \supset P'$ and G is arc consistent wrt P''
- **Theorem**: The largest arc consistent domain exists and is unique

AC-5

- AC-5 is a *generic* arc consistency algorithm
 - uses two abstract procedures ArcCons and LocalArcCons
 - can be specialized to either AC-3 or AC-4
 - can be specialized to exploit properties of constraints (e.g., functional, anti-functional, monotonic constraints)

Queue elements in AC-5

- AC-5 maintains a *queue* of elements of the form ((i, j), w)
 - -(i, j) is an arc, and w is a value in D_j that has been removed justifying the need to reconsider arc (i, j)
 - Enqueue(j, Δ , Q) inserts all elements of the form ((i, j), w) onto the queue Q such that (i, j) is an arc and $w \in \Delta$



ArcCons and LocalArcCons

function ArcCons(i, j)

Returns $\Delta = \{ v \in D_i / \forall u \in D_i \neg C_{ij}(v, u) \}$

- Removing elements in Δ from D_i makes (i, j) arc consistent

function *LocalArcCons(i, j, w)*

Assumes that w has been removed from D_j

Returns Δ such that $\Delta_2 \supseteq \Delta \supseteq \Delta_1$ where

$$\Delta_{I} = \{ v \in D_{i} / C_{ij}(v, w) \text{ and } \forall u \in D_{j} \neg C_{ij}(v, u) \}$$

$$\Delta_{2} = \{ v \in D_{i} / \forall u \in D_{j} \neg C_{ij}(v, u) \}$$

Arc consistency with AC-5

```
procedure AC-5(G)
   InitQueue(Q)
   for each (i, j) \in arc(G) do
       \Delta = ArcCons(i, j)
       Enqueue(i, \Delta, Q)
       Remove(\Delta, D_i)
   endfor
   while not EmptyQueue(Q) do
       ((i, j), w) = Dequeue(Q)
        \Delta = LocalArcCons(i, j, w)
       Enqueue(i, \Delta, Q)
       Remove(\Delta, D_i)
   endwhile
end AC-5
```

Nayak

Counting queue operations in AC-5

- Introduce the *Status* of (*edge*, *value*) pairs such that
 - InitQueue sets Status((k, i), v) = present if v in D_i = rejected otherwise
 - Enqueue sets the Status of each queued item to suspended
 - Dequeue sets the Status of dequeued item to rejected
- AC-5's loops preserve the invariant that Status((k, i), v)

```
= present iff v \text{ in } D_i
```

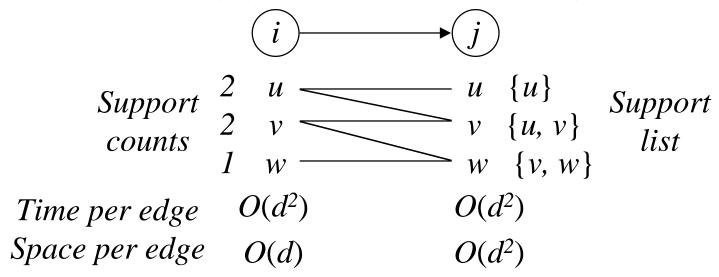
- = suspended iff v not in D_i and ((k, i), v) on the Q
- = rejected iff v not in D_i and ((k, i), v) not on the Q
- \Rightarrow AC-5 enqueues and dequeues at most O(ed) items

AC-3

- For arbitrary constraints ArcCons is $O(d^2)$
- *AC-3* is essentially *AC-5* in which *LocalArcCons* is implemented using *ArcCons*
- \Rightarrow AC-3 is $O(ed^3)$

AC-4

• If ArcCons is $O(d^2)$ and LocalArcCons is O(d)then AC-5 is $O(ed^2)$



- LocalArcCons(i, j, w) iterates through the "supports list" of w for edge (i, j), decrements "support counts", and computes Δ as the set of values whose "support counts" go to 0
- \Rightarrow LocalArcCons is O(d) and ArcCons is $O(d^2)$ so AC-4 is $O(ed^2)$

Functional constraints

• A constraint C is functional wrt a domain D iff for all $v \in D$ there exists at most one $w \in D$ such that C(v, w)

Classes of constraints

- Other classes of constraints for which AC-5 is O(ed)
 - anti-functional
 - monotonic
 - piecewise functional
 - piecewise anti-functional
 - piecewise monotonic